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17	4862	((700/2,3,4,11,20) or (709/205,248)).CCLS.	USPAT;	2004/07/09 11:37
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			IBM TDB	
18	27228	program near generat\$3	USPAT;	2004/07/09 11:37
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			DERWENT;	
			IBM TDB	
19	163	(((700/2,3,4,11,20) or (709/205,248)).CCLS.)	USPAT;	2004/07/09 11:37
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			IBM TDB	
20	221	(717/162).CCLS.	USPAT;	2004/07/09 11:38
		(11,1202,100201	US-PGPUB;	1 2002, 01, 05
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21	348	(717/120,121,122).CCLS.	USPAT;	2004/07/09 11:38
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22	264	(((717/162).CCLS.) ((717/120,121,122).CCLS.)	USPAT:	2004/07/09 11:39
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23	20242	shingt with ghand?	IBM_TDB USPAT;	2004/07/09 11:39
23	30342	object with shar\$3	US-PGPUB;	2004/07/09 11:39
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24	32	((((717/162).CCLS.)	1	2004/07/09 11:39
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ا م	^	generat\$3)) and (object with shar\$3)	IBM_TDB	2004/07/00 11 55
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26	14	"08289"	USPAT;	2004/07/09 11:56
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27	0	denki and kabushidi and kaisha	JPO	2004/07/09 11:57
28	0	denki and kabushidi	JPO	2004/07/09 11:57
29	6	denki and kaisha	JPO	2004/07/09 11:57
30	2	kabushiki and kaisha	JP0	2004/07/09 11:58
31	15082	akiyoshi kabe	JPO	2004/07/09 11:58
32	0	"akiyoshi kabe"	JPO	2004/07/09 11:58

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1 Path Planning and Control of a Cooperative Three-Robot System Manipulating Large Objects

Costas S. Tzafestas, Platon A. Prokopiou, Spyros G. Tzafestas June 1998 Journal of Intelligent and Robotic Systems, Volume 22 Issue 2

Full text available: Publisher Site

Additional Information: full citation, abstract

After a brief review of the current research on multi-robot systems, the paper presents a path planning and control scheme for a cooperative three-robot system transferring/manipulating a large object from an initial to a desired final position/orientation. The robots are assumed to be capable of holding the object at three points that define an isosceles triangle. The mode of operation adopted is that of a "master-and-two-slave robots". The control scheme employs the diffe ...

Keywords: cooperative three-robot system, large object manipulation, master-and-twoslaves mode, multi-robot systems, path planning-control

Exception-based information flow control in object-oriented systems Elisa Bertino, Sabrina De Capitani Di Vimercati, Elena Ferrari, Pierangela Samarati November 1998 ACM Transactions on Information and System Security (TISSEC), Volume 1 Issue 1

Full text available: pdf(457.22 KB)

Additional Information: full citation, abstract, references, citings, index terms, review

We present an approach to control information flow in object-oriented systems. The decision of whether an information flow is permitted or denied depends on both the authorizations specified on the objects and the process by which information is obtained and transmitted. Depending on the specific computations, a process accessing sensitive information could still be allowed to release information to users who are not allowed to directly access it. Exceptions to the permissions and restricti ...

Keywords: access control, condifentiality, information flow control, object-oriented databases and systems

3 Semantic Based Concurrency Control of Open Nested Transactions in Active Object Oriented Database Management Systems

Prithwish Kangsabanik, R. Mall, A. K. Majumdar April 2000 Distributed and Parallel Databases, Volume 8 Issue 2

Full text available: Publisher Site

Additional Information: full citation, abstract, index terms

Active object oriented database management systems (AODBMS) are finding increasing